



MATEKSYS

FLIGHT CONTROLLER F722-WPX

QUICK START GUIDE

MCU: 216MHz STM32F722RET6

IMU: MPU6000 (SPI)

Baro: DPS310 (I2C)

OSD: Pixel OSD/FrskyOSD (Uart6)

Blackbox: MicroSD socket (SPI)

6x UARTs(5 Spare) with built-in inversion

1x Softserial_Tx option

10x PWM outputs

1x I2C

4x ADC (VBAT, Current, RSSI, AirSpeed)

1x SH1.0_6pin connector (4V5/G/TX4/RX4/SDA/SCL) for GPS/compass

1x SH1.0_6pin connector for external USB and buzzer

Switchable Dual Camera Inputs

Switchable Vbat for Camera/VTX

6~30V DC IN (2~6S LiPo)

132A high-precision Current Sense

BEC 5V 2A for FC & Peripherals

BEC Vx 5A for servos, 5V/ 6V option

Vbat filtered output 1A for VTx and Camera

LDO 3.3V 200mA

INAV Target MATEKF722WPX

LAYOUT

+ & - : Battery & ESC power pads, 6~30V DC(2~6S LIPO).

Battery Voltage Sensor: 1K:10K, Scale 1100
Current Sensor: 132A, 3.3V ADC, Scale 250
Current Sense resistor: 0.5mR, 60A continuous, 132A burst.

INAV Plane mixer
S1/S2: ESC signal
S3/S4/S5/S6/S7/S8: Servo signal

Vx: BEC 5V/6V for servos, 5A cont.
Default is 5V

Rx1: UART1_RX for ESC telemetry
DO NOT connect the ESC onboard BEC output(Red wire) to Rx1 pad.

AirS: Analog Airspeed sensor
(0~6.6V)

1: 1 voltage divider built-in
LED: 2812 LED signal output
Rssi: Analog RSSI IN
CCtr: Not support

SCL / SDA: I2C1

*** compass QMC5883/ HMC5883 / MAG3110 / IST8310 / LIS3MDL
*** Digital AirSpeed sensor Pitot_MS4525
*** OLED 0.96"

3V3: LDO3.3V 200mA

5V: onboard BEC 5V 2A cont. Max.3A

4V5: 4.4~4.8V, Max.500mA

*** the voltage is also supplied when connecting via USB

Tx3/Rx3: UART3_TX & RX
Tx5/Rx5: UART5_TX & RX

RX2: UART2_RX for Serial RX by default, PPM share RX2 pad
TX2: UART2_TX w/o CPU based serial ports enabled
TX2: Softserial_TX1 w/ CPU based serial ports enabled

*** F722 all UARTs have built-in inversion, SBUS can be connected to any spare UART_RX.

*** Frsky FPort, SmartPort, Tramp & SmartAudio can be connected to any spare UART_TX

INAV Plane mixer
S9/S10: Servo signal

LED 3.3: Red, 3.3V Status
LED 0: Blue, FC Status
LED 1: Green, FC Status

Vbat: Filtered battery voltage
*** ON/OFF switch via Modes/USER1
*** Max.1A load on this rail. (Default ON)

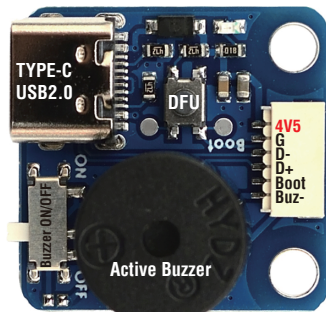
VTx: Analog Video OUT to Video Transmitter

C1: Camera-1 video IN (Default)

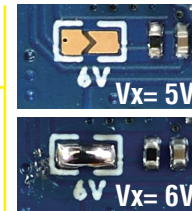
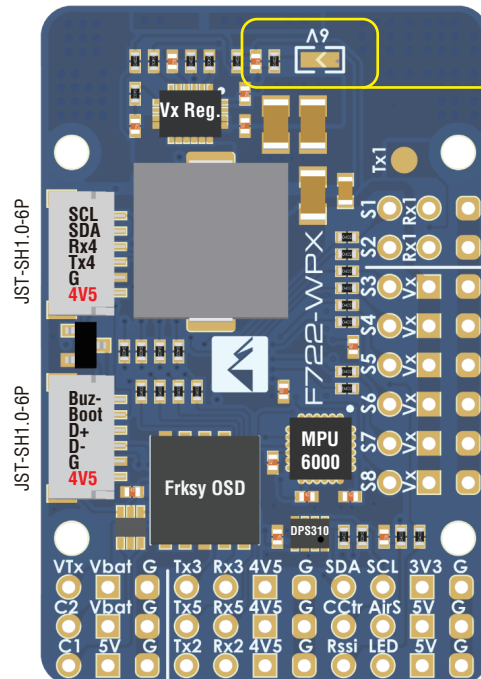
C2: Camera-2 video IN

*** C1/C2 switch via Modes/USER2

*** Two cameras should use identical video format, both PAL or both NTSC
*** Double check out Camera signal and power cables before powering them up.



Φ3mm, 16mm mounting



Tx1/Rx1: UART1_TX & RX

Size: 44x29x10mm
Weight: 20g w/ bottom plate & USB extender
Holes: Φ2mm, 25mm mounting

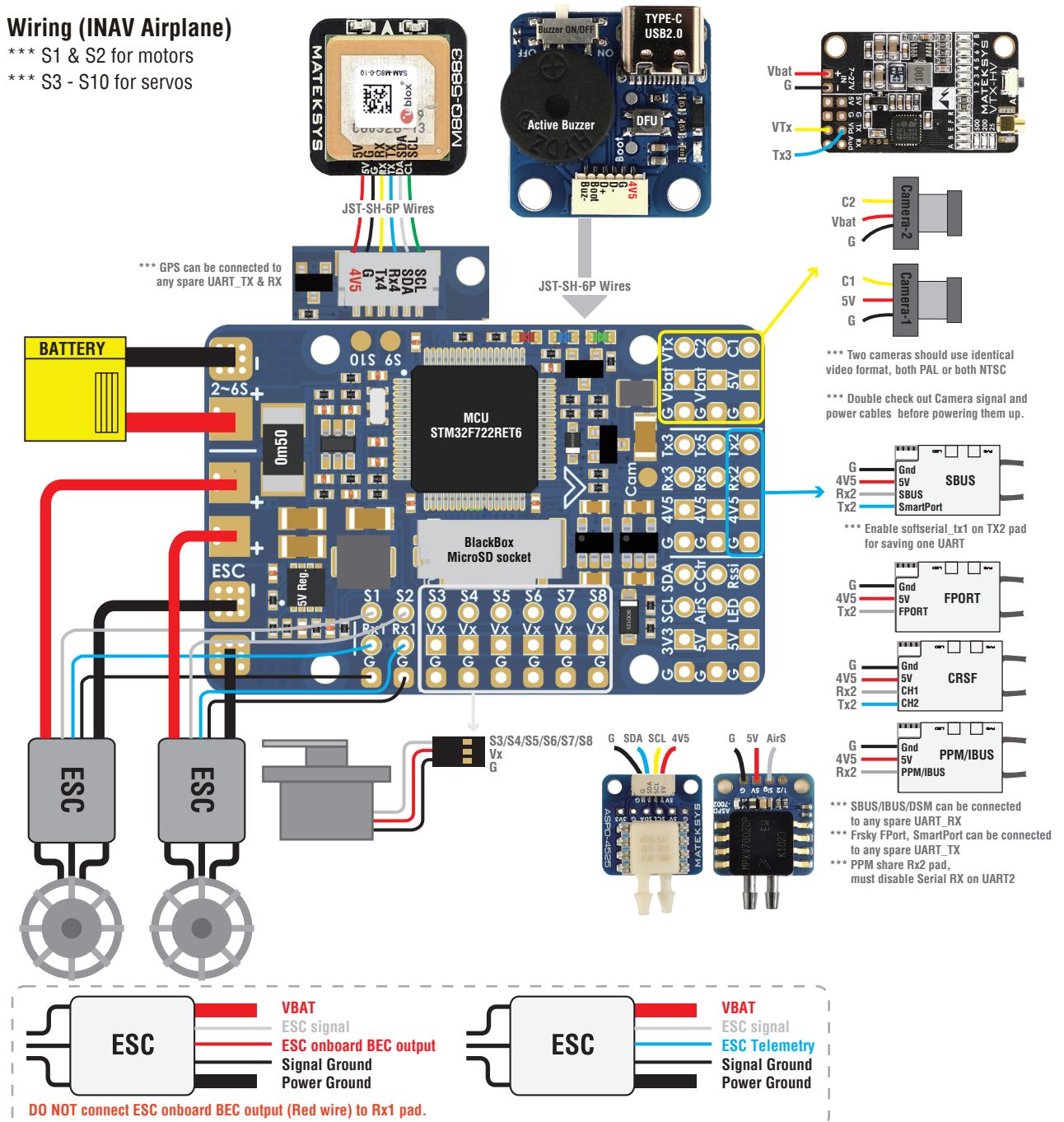
INAV Target: MATEKF722WPX

*** CLI defaults after reflashing

Wiring (INAV Airplane)

*** S1 & S2 for motors

*** S3 - S10 for servos



Identifier	Data	Telemetry	RX	Sensors	Peripherals
USB VCP	☒ MSP 115200	Disabled	AUTO	☒ Serial RX	Disabled
UART1	☐ MSP 115200	Disabled	AUTO	☐ Serial RX	Disabled
UART2	☐ MSP 115200	Disabled	AUTO	☒ Serial RX	Disabled
UART3	☐ MSP 115200	Disabled	AUTO	☐ Serial RX	Disabled
UART4	☐ MSP 115200	Disabled	AUTO	☐ Serial RX	Disabled
UART5	☐ MSP 115200	Disabled	AUTO	☐ Serial RX	Disabled
UART6	☐ MSP 115200	Disabled	AUTO	☐ Serial RX	Disabled
SOFTSERIAL1	☐ MSP 115200	SmartPort	AUTO	☐ Serial RX	Disabled

Current Sensor

☒ Battery current monitor

250 Scale the output voltage

0 Offset in millivolt steps

0.20 Battery Current

FrskyOSD is enabled on UART6 by default
Do not change it.

Vbat Power / Camera switch

USER1	No USER1 definition Vbat ON by default
USER2	No USER2 definition C1 (Camera-1) ON by default

USER1 CH 8 Vbat OFF Vbat ON

USER2 CH 5 C1 ON & C2 OFF C2 ON & C1 OFF